

# Real-time Small Aircraft Transportation Systems (SATS) engineering test bed for the definition, development, and validation of operations using an Airborne Internet (AI) architecture

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# Presentation outline

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- Background - simulation objective
- Assumptions of SATS objectives
- Current simulation capability
  - « Engineering test bed features
  - « What can be tested and developed
- Near term upgrade (Phase I)
- End-state architecture (Phase II)
- Example



# Background - Simulation objective

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NASA, FAA, State and local aviation organizations in partnership to support research and development focused on maturing SATS enabling technologies. Simulation test bed support objectives

- Higher volume operation at non-towered/non-radar airports
- Lower landing minima at minimally equipped landing facilities
- Increase single-pilot crew safety and mission reliability.
- En route procedures and systems for integrated fleet operations.



# SATS Assumptions I

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## ***Higher volume operation at non-towered/non-radar airports***

Underlying the Higher Volume Operations (HVO) is a newly defined area of flight operations called an HVO Self Controlled Area (SCA) for SATS airports.

**Initial goal:** *Five simultaneous operations in non-radar airspace*

## **Assumptions**

- All HVO aircraft have a minimum approved set of equipment
- Pilots assume responsibility for self-separation
- HVO airport has an Airport Management Module
- Airport has automatic weather observing/reporting capability.
- Operations may be conducted in IMC
- No special provision required for separation from non-participating traffic (“see and avoid” in effect per FAR Part 91.113)
- Approaches are “published” may be sent from the ground from a pre-approved set and are not dynamically calculated



# SATS Assumptions II

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Lower landing minima at minimally equipped landing facilities

Increase single-pilot crew safety and mission reliability

## Assumptions

- All HVO aircraft have a minimum approved set of equipage
- Pilots assume responsibility for self-separation
- HVO airport Airport Management Module **can provide integrity and/or navigation guidance verification**
- Airport has automatic weather observing/reporting capability.
- Operations may be conducted in IMC
- No special provision required for separation from non-participating traffic (“see and avoid” in effect per FAR Part 91.113).
- Approaches are “published” (they may be sent up from the ground from a pre-approved set and are not dynamically calculated)
- **Crew safety and mission reliability can be supported and/or monitored by data link facilities at SATS facilities**



# SATS Assumptions III

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En route procedures and systems for integrated fleet operations

## Assumptions

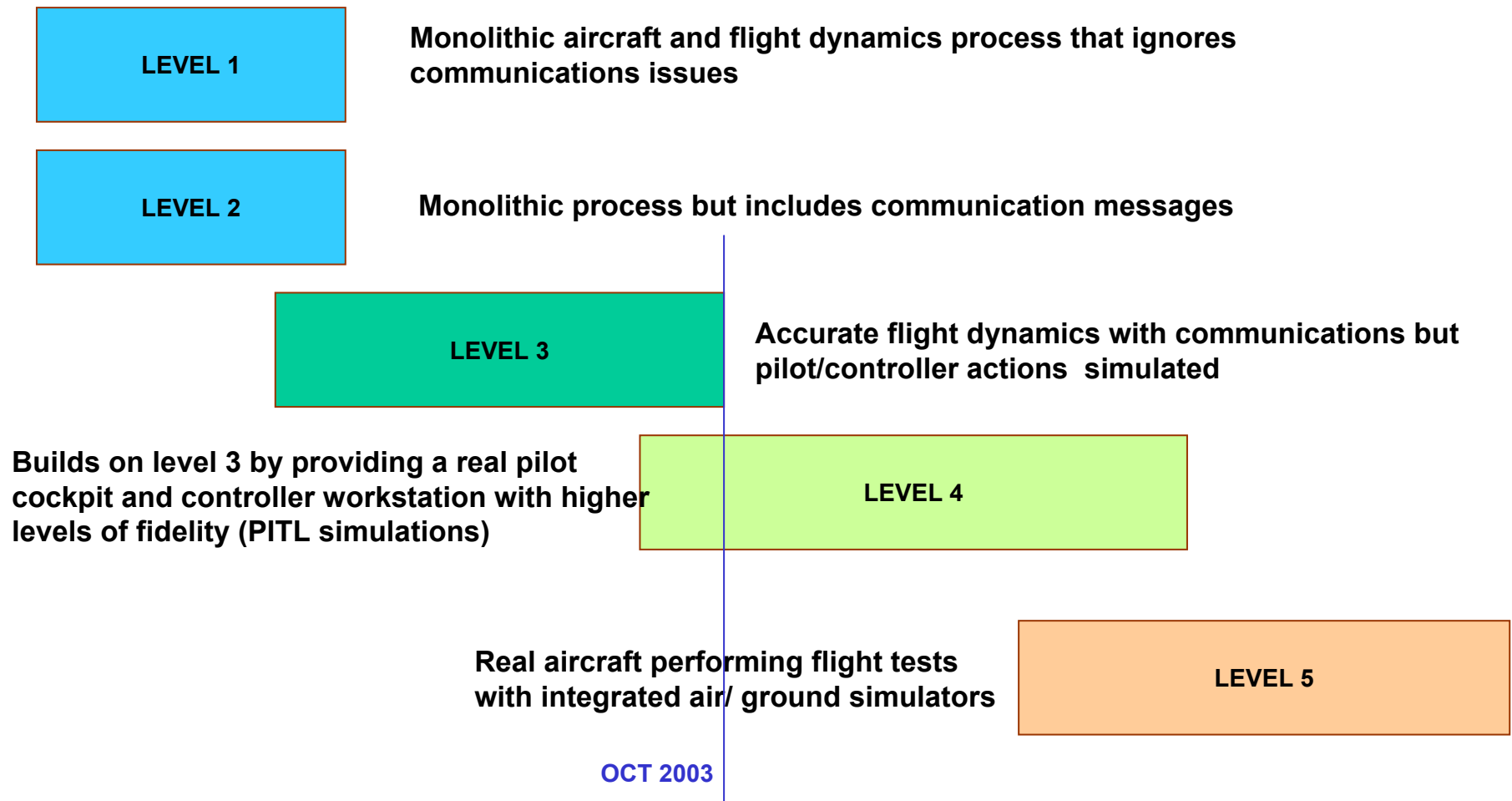
- ➔ HVO airport has an Airport Management Module
- ➔ **Data link connectivity to aircraft is maintained for ATC transfer of control (ingress and egress) from SATS/ SCA**
- ➔ Airport has automatic weather observing/reporting capability.
- ➔ Operations may be conducted in IMC
- ➔ **In the en route phase of flight, if the aircraft is operating under IFR it is assumed the aircraft is under positive ATC control**
- ➔ **Operations are conducted under FAR Part 91 as much as possible.**
- ➔ No special provision required for separation from non-participating traffic (“see and avoid” in effect per FAR Part 91.113).
- ➔ Approaches are “published” (they may be sent up from the ground from a pre-approved set and are not dynamically calculated).



# Simulation capability

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## Simulation Levels





# Engineering test bed I

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Communications architecture builds on AI concepts and includes functionality required for HVO SATS radios

- ADS-B and CDTI
- GPS
- Datalink
- uplink broadcast datafeed (broadcast FIS-B)
- downlinked datafeed acknowledgements
- air/air, air/ground, and ground/air messaging for e-mail, IP traffic, CPDLC and chat messages





# Engineering test bed II

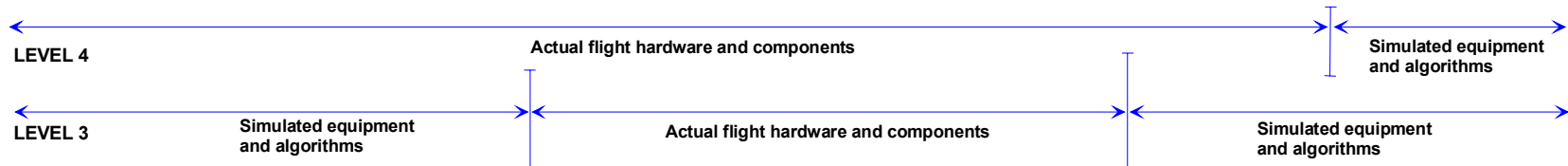
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Other development engineering components integrated presently include:

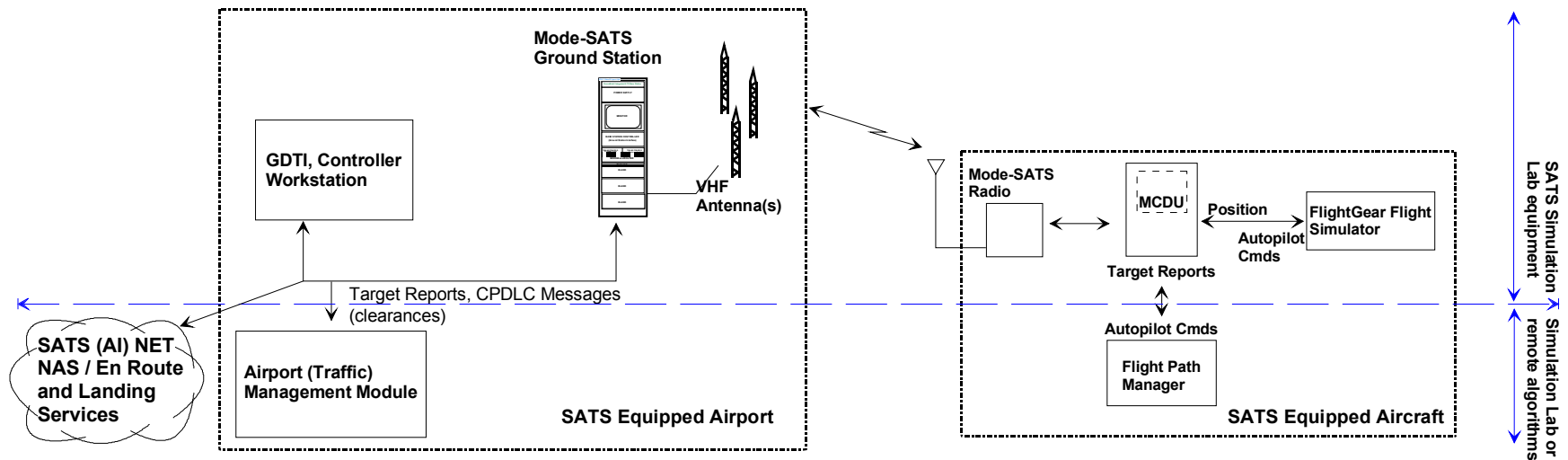
- ✈ Modified FlightGear flight simulator is a sophisticated flight simulator framework developed with NASA Glenn
- ✈ The Multi-Function Control and Display Unit (MCDU) (converts uplinked commands into directions to the FlightGear)
- ✈ Flight Path Manager (receives ADS-B position reports)
- ✈ Airport Management Module (resides in the ground station or is remotely located on researcher's computer)
- ✈ Datalink to TCP/IP networks (Firewall, VPN and RMM)
- ✈ The Ground Display of Traffic Information (allows simulation director to monitor performance of simulation)
- ✈ Research IP network (provides simulation monitor, software, data transfer and logging)

# Current test bed features

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Real-time Small Aircraft Transportation System (SATS) Airborne Internet Engineering Test Bed



## CURRENT LAB EQUIPAGE



# What can be tested now I

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Allows HITL and PITL testing of:

- airborne internet functionality and performance
- airborne automation
- ground automation
- pilot/automation interaction
- controller/automation interaction
- pilot/pilot and pilot/controller procedures interaction
- procedures for en-route/SCA and SCA/en-route transitions



# What can be tested now II

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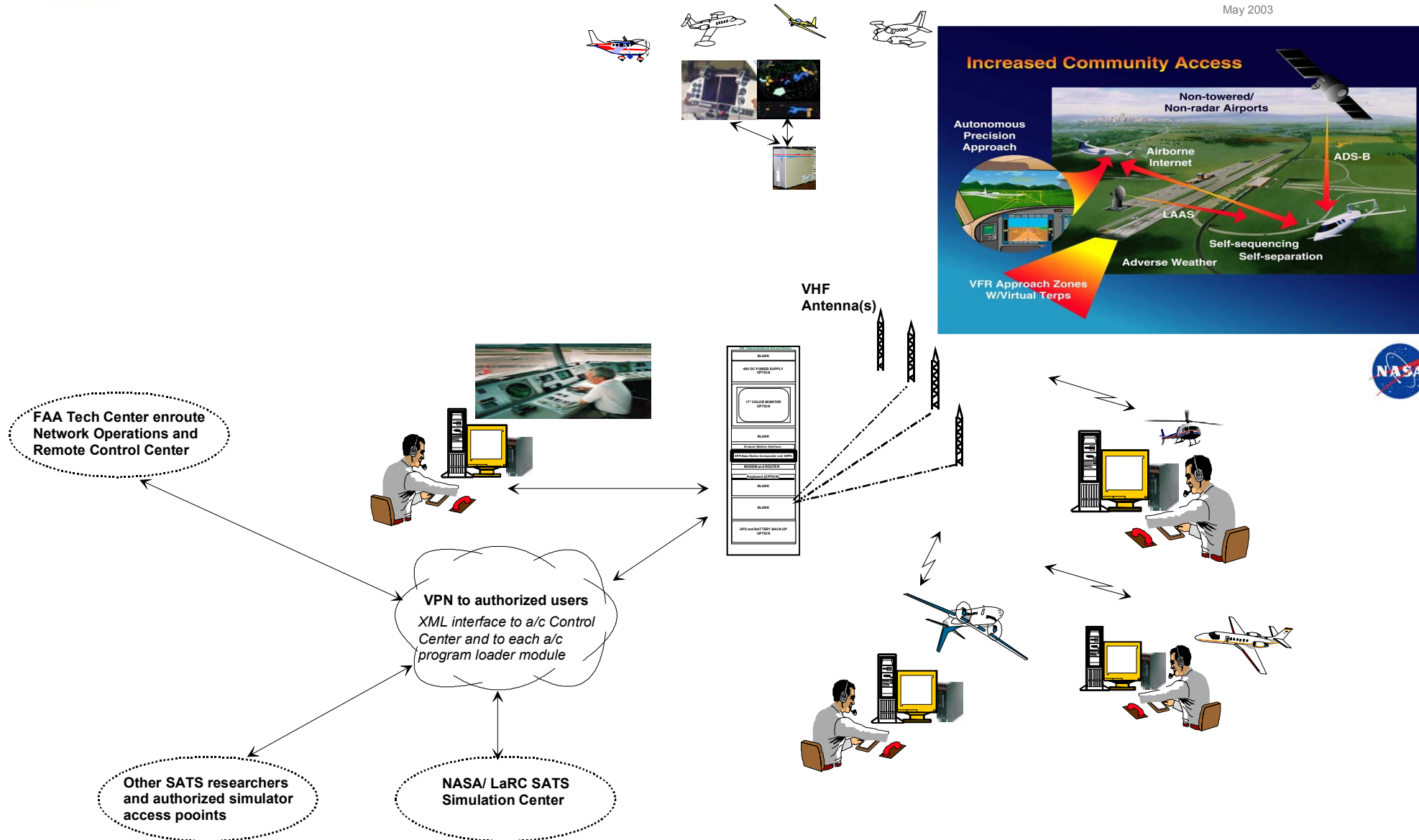
## Additional features:

- ✈ Downlink acknowledgement of uplink broadcast FIS-B transmissions
- ✈ Different sequencing of FIS-B data based upon aircraft location, priority of the uplinked data, and other factors
- ✈ Text-to-speech of uplinked data (minimize head-down time)
- ✈ Remote development of airborne automation
- ✈ Remote development of ground automation
- ✈ PITL simulation



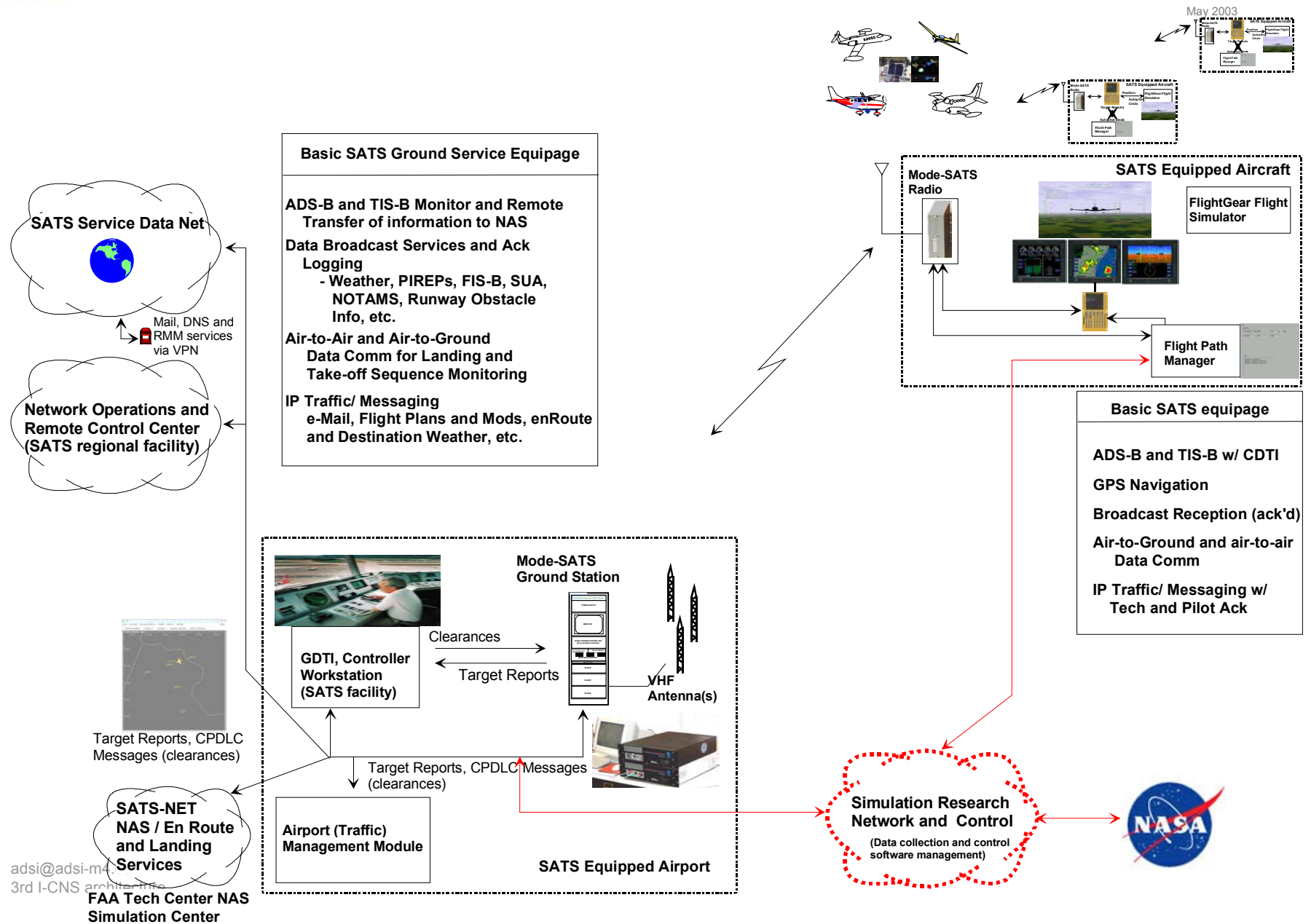
# Simulator Conops View

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# Level 4 simulator components





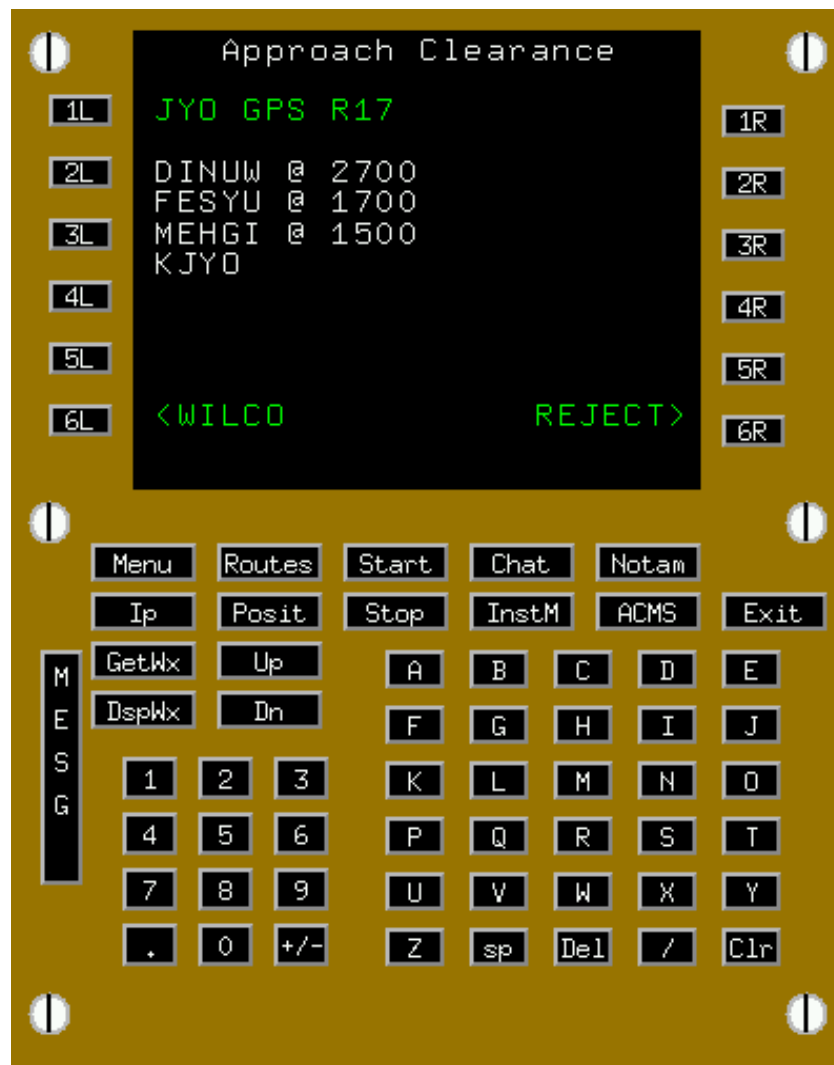
# An example

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Cessna-310 (N507NA) is making an approach to  
Leesburg Airport (JYO).

# An example

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# An example

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File

N507NA

18.410870,-77.628024 JYO Rte

47725 197 120

Log

N507NA< entered SCA  
N507NA< request JYO GPS R17  
N507NA> cleared JYO GPS R17

# An example

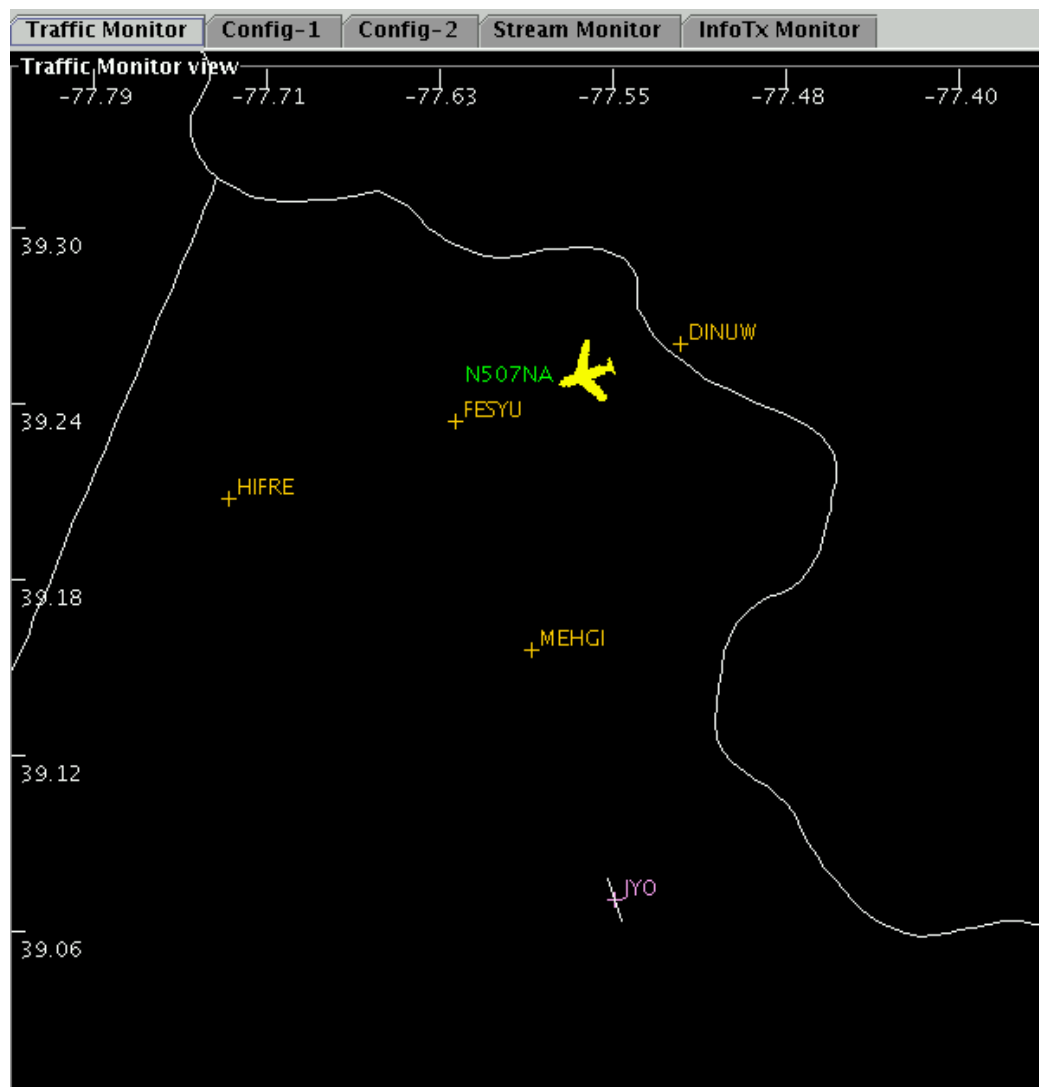
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# An example

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# Future work

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- ✈ Support the NASA HVO development program
- ✈ Participate in the VASATSLab program
- ✈ Continued development of the ADN concept and simulations in support of the AI Forum
- ✈ Progress simulator from Level 3 to Levels 4 and 5